

Towards Low Energy Mobility Using Light and Ultralight Electric Vehicles.

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Part 1

General view:

Conventional Vehicles
compared with electric and
light electric vehicles

History



- 9 parts of rivetted partinium:
Aluminium Tungsten alloy,
laminated with magnesium
- DC drive without differential
- Pb accumulators 100x2V (for
2000m long)
- No steering wheel, but 2 handles
- No mechanic brakes

“la jamais contente” 1899
Camille Jenatzy Belgian
electric, $\pm 1400\text{kg}$
First 105km/h ,at Achères France

History



Batteries at the bottom,
Chain transmission
Wooden frame, chain
reduction.
“Natural fibre”

“<- Camille Jenatton Belgian
electric “Beer truck” Wieze, about 1905
Wieze-Brussels at 5km/h

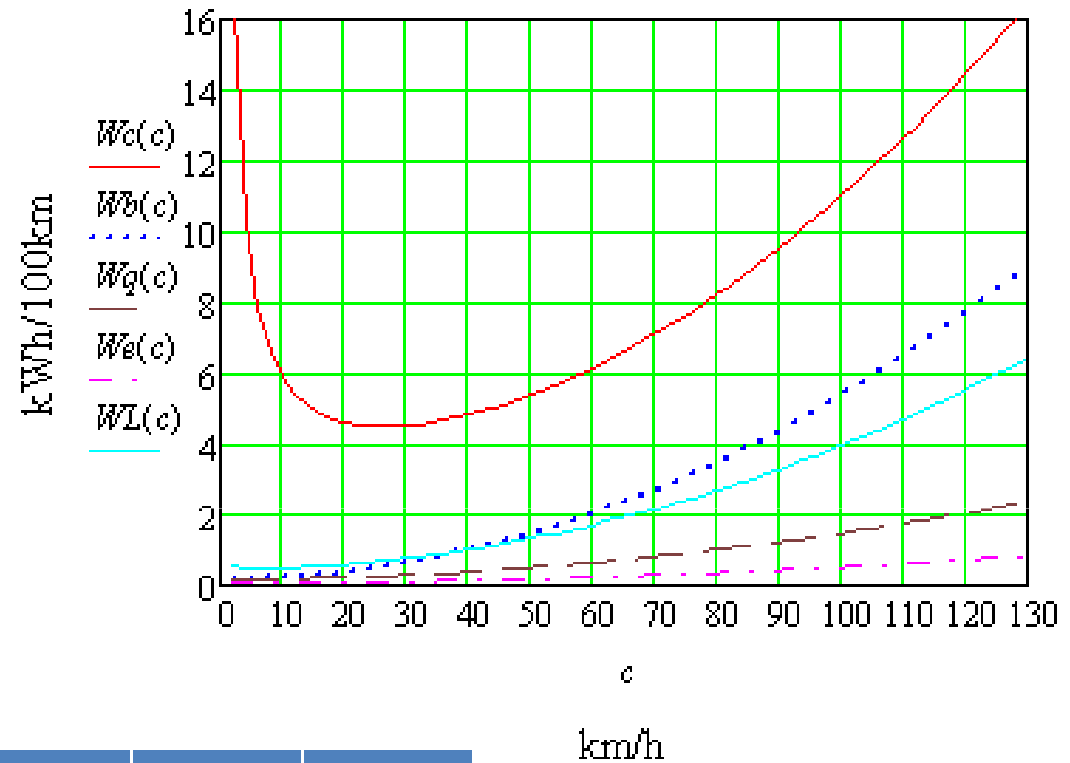
kWh/100km mechanical need?



Energy 5 Hogent



Quest Velomobiel



type	curve	M [kg] Curb + user	Fc [./.]	S [m ²]	Cx
Today car	Wc	1200+100	0.008	2	0.3
E-bike	Wb	25+85	0.006	0.5	0.8
Quest	Wq	39+85	0.005	0.22	0.47
Energy5	We	60+55	0.002	0.136	0.254
Elbev	WL	100+100	0.008	0.9	0.3

“Elbev”

Ecologic low budget electric vehicle

Ultralight electric vehicle

Low budget development: Partners: Ugent EELAB – Hogent Electromechanics

Target Specifications

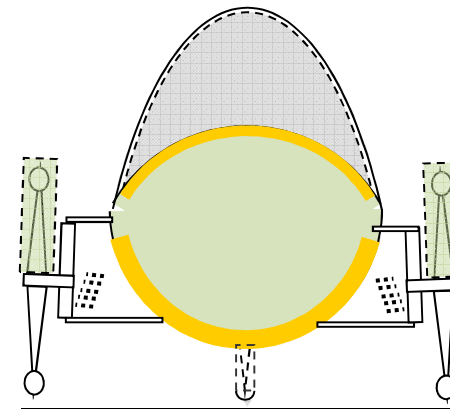
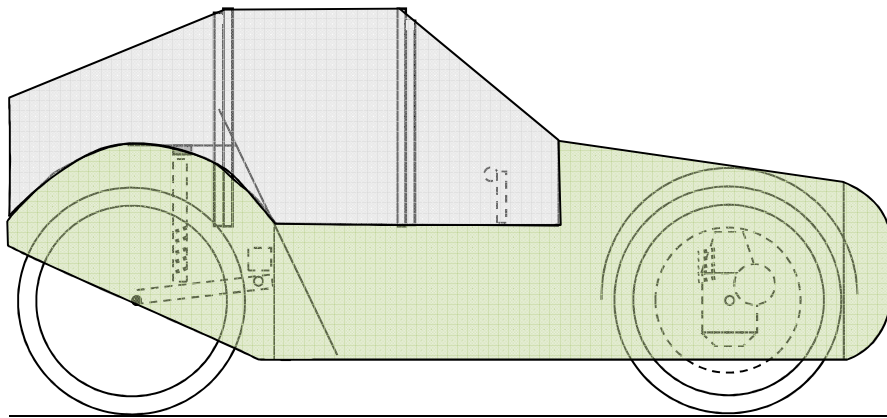
- Single person (for the moment)
- about 100 kg
- Three wheel: two driven front wheels, one back
- Speed range 70-80km/h
- Gradability $\geq 20\%$
- Acceleration: about 0-50km/h in 8 seconds
- Consumption 2kWh/100km country side, 3kWh/100km city
- Drive: front wheel high efficiency BLDC 2x4kW peak , motor weight 1.6 kg/motor
- Elements as safety, avoiding 12V battery....
- 2 times 48V 20Ah Li-ion in series (one can add more)



Elbev concept

Ecologic low budget electric vehicle

EELAB Ugent original concept; project with Hogent



Elbev: impression, intended for 0.5m^2 cross section,
(but it became 0.9m^2 with more space)

Electric vehicles

	kWh/100km At wall plug	Curb weight kg
Electric bike	1 (+0.5 human)	20...30kg
elbev	2-3 (3 city)	80...100
Light high efficiency 4 person	10	800
Normal With high efficiency drive	15	1300
Heavy With normal efficiency	20	1800
Electric SUV	25	>2000

Ultralight and light vehicles

As far as possible, the vehicle should weight less or equal to the usually transported goods

	Ultralight [kg/person]	Light [kg/person]	Normal [kg/person]
Electric bike Weight/person	20	25	30
Non-covered 3-4 wheel Electric vehicle	<60	<120	200
Covered 3-4 wheel	<100	<200	300



E-Bikes satisfy perfectly, but are non covered (rain and cold)
Single or two person vehicles, 3,4,5,6 person?
Why not apply the kg/person gradually also to public transport?

Ratio Electric / fuel engines?

- 1 liter of gasoil Diesel = 35.94 MJ/liter

(=42.91MJ/kg LHV density 837 kg/m³)

http://www.academia.edu/1073990/The_Energy_and_Fuel_Data_Sheet

- 1 liter of Gasoline (Benzine)= 32.7 MJ/liter

44.15MJ/kg LHV density 741 g/m³ ,

http://www.highlandfuels.co.uk/downloads/Esso_Super_Plus_ULS_Petrol_Spec_Sheet.pdf

- Electricity 3,6MJ/kWh

- For non-specialists:

1liter of fuel \cong 1m³ of natural gas \cong 10kWh

Gasoline 0.18 and diesel fuel in Belgium \cong 1.45 Euro/kWh heat

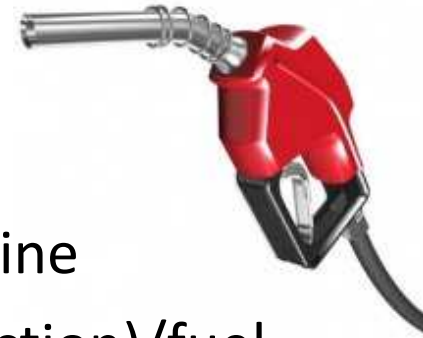
Night tariff electricity \cong 0.17Euro/kWh, so similar for heat.

So efficiencies can be directly compared So

More: http://en.wikipedia.org/wiki/Fuel_efficiency



Efficiency of conventional engines?



- Combustion engines in cars,
typical maximum 35% for diesel, 30% for gasoline
- Practically, in actual efficient cars, (air + tire friction)/fuel
14% for a diesel, (5 liter/100km, 2% equivalent slope, 1300kg)
$$0.02 * 9.81 * 1300 * 10^5 / (35.94 * 5) = 14.2\%$$

13% for gasoline (5.5 liter/100km, 2% equivalent slope, 1050kg)
$$0.02 * 9.81 * 1200 * 10^5 / (32.7 * 5.5) = 13.1\%$$
- Mobility efficiency?
x usefull weight/total weight
For one person in a car: 1.09% diesel, 1.09% gasoline so typical 1.1%
- Ecologic efficiency?
Even a factor 2 lower due to manufacturing energy

Efficiency of Electric Cars?



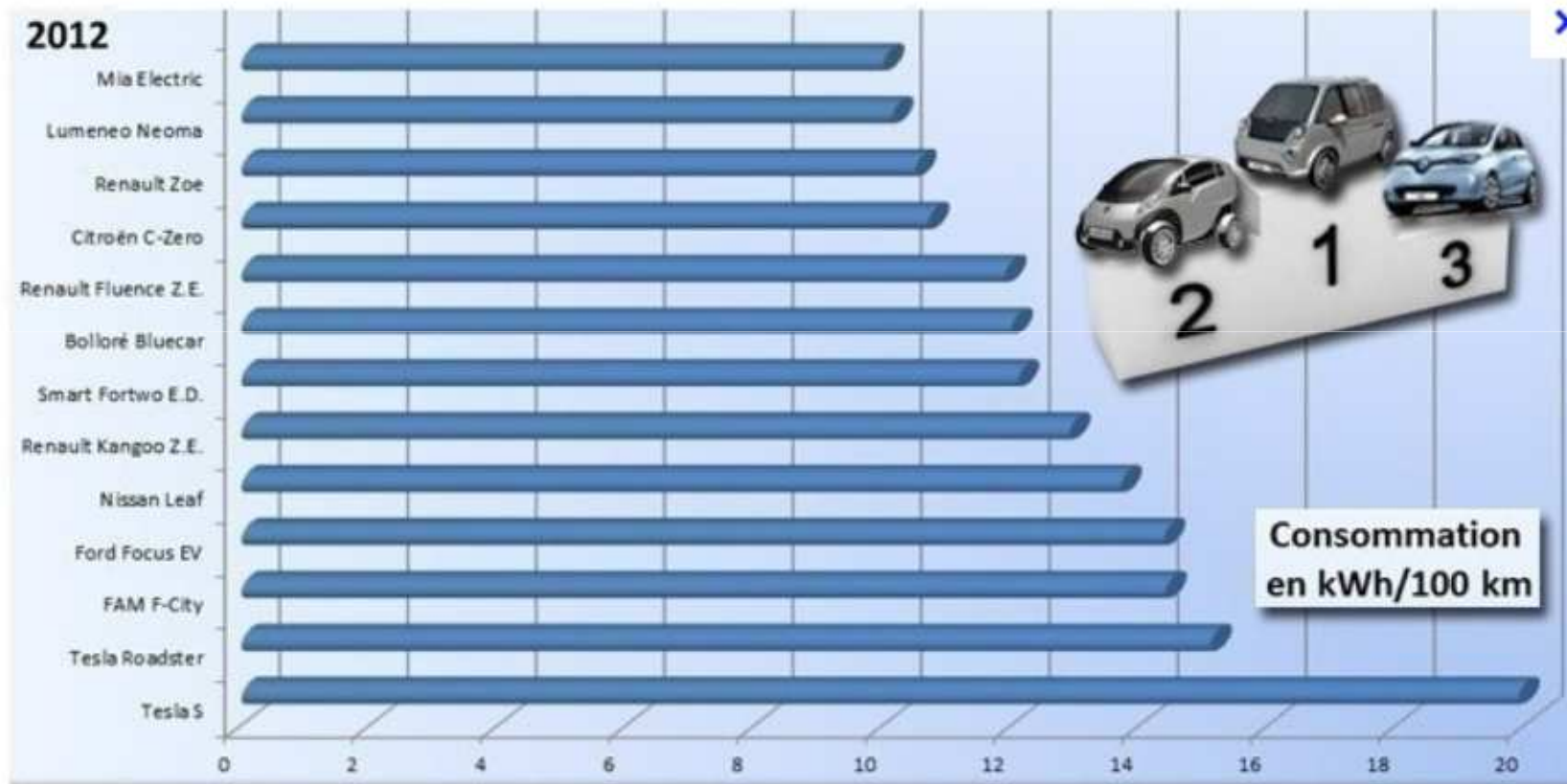
- Maximum efficiency of charger, battery, converter, motor=
 $95 \times 90 \times 96 \times 90 = 74\%$
- Practically in real conditions 50-60% in high efficiency drives,
<40% in average efficiency drives.
- Mobility efficiency;
Normal for 50% and 100kg usefull on 1400kg total **3.57%**
Ultralight for 60% and ultralight 100kg on 200kg total **30%**
Ecologic: probably factor 3 lower if manufacturing energy is considered
- Fuel efficiency of electricity?
1kWh electricity is traditionally considered be generated by 40% efficiency
But a combined cycle at night: 59%, with 10% transmission loss =>53.1%?



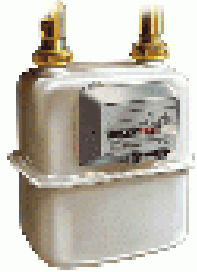
Efficiency of Electric Cars?

Mechanical needs/0.6?

Down to 10kWh/100km?



www.technologyvehicles.com



Gas? or convert Gas to Electric First?



- Make first electricity with natural gas or use it directly?

Using CNG directly (compressed natural gas) in vehicles:

5% electricity so rather 9% gas equivalent to compress NG at 200 bar,

Fiat Punto <http://www.cngas.co.uk/cngvehicles.php>

3.9 kg/100km but 5% of energy in electricity to compress at 55% efficiency is 9%

Nat. Gas is 4.25 kg gas

First convert gas to electricity?

1kg CNG = 45.86 MJ/kg LHV at 59%, 10% losses at night in distribution

24.35MJ electricity at wall plug

$45.86 \times 0.59 \times 0.9 / 3.6 = 6.76$ kWh/kg

An electric car needs about 10kWh/100km = 1.48kg CNG/100km

*Factor **2.87** longer distance,*

*But even **11.5** times if an ultralight EV of 2.5kWh/100km is used.*



Some primary conclusions:

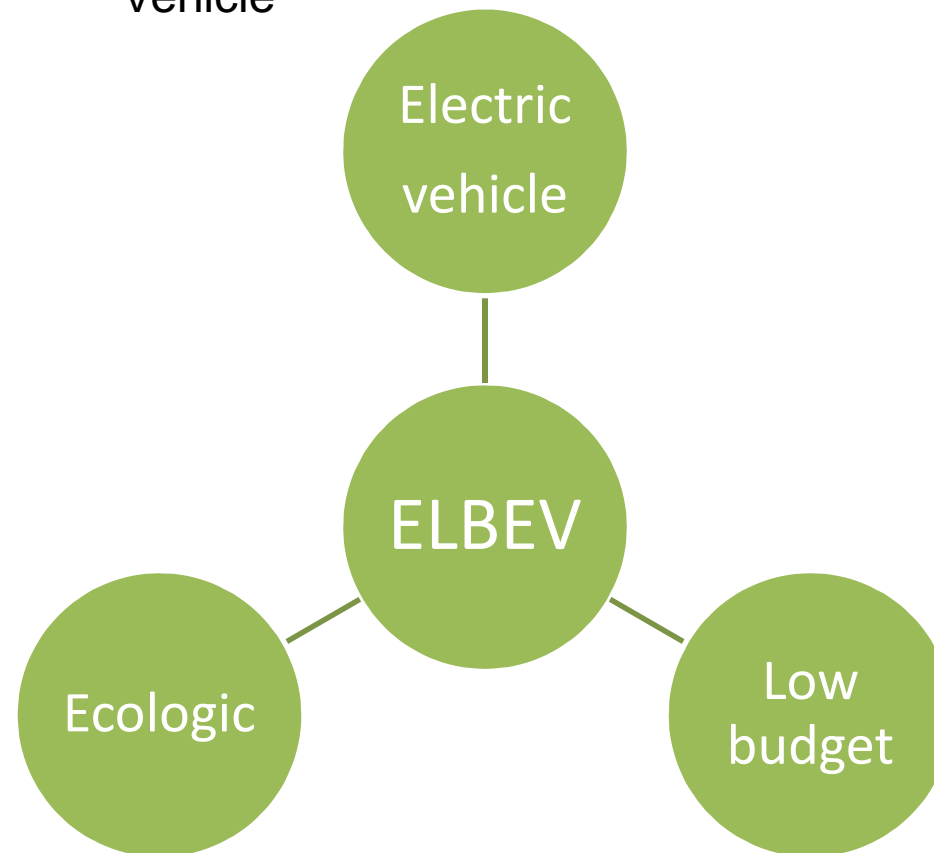
- ❖ The worst electric car needs about the same prime energy than a conventional fuel cars. But possibly less CO₂ if the electric energy mix is considered.
- ❖ Lightweight vehicles can do 10 times better in primary fuel and 20 times better in fuel cost/100km
- ❖ There is still room for optimizing classical cars in hybrid if it the total weight is also reduced.

Part 2

Focus on ELBEV: “Ecologic Low Budget Electric Vehicle”

Research project

Ecologic Low Budget Electric
Vehicle



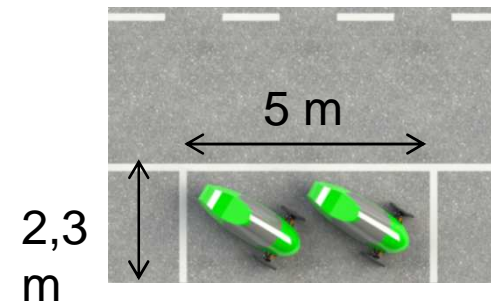
ELBEV

WHAT ?

- Electric single person vehicle, mainly for commuting purposes
- Three wheels
 - One rear
 - Two driven and steering front wheels
- Curb weight ± 100 kg
- Maximum speed 70 km/h
- Range ± 100 km
 - City and suburbs

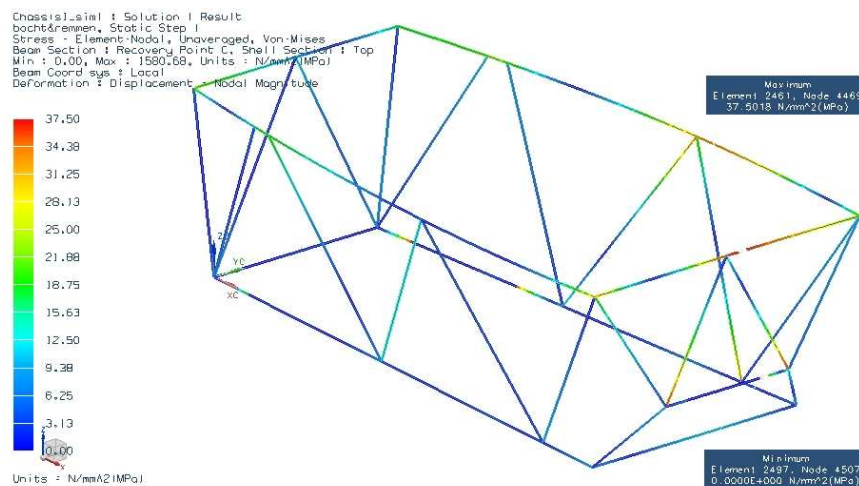
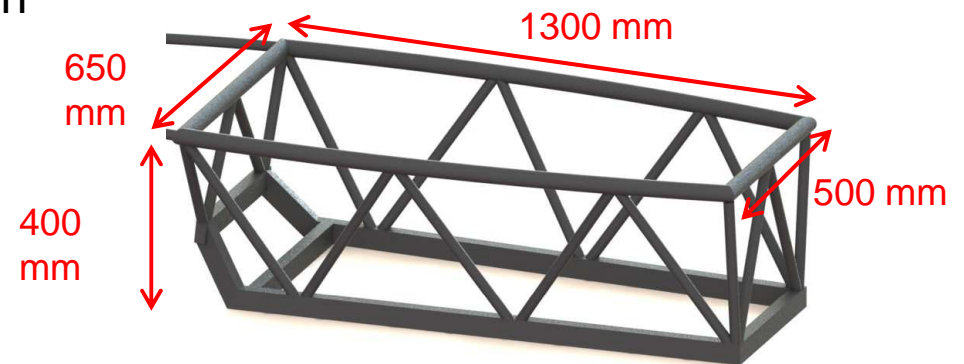
DIMENSIONS

- Total length 2200 mm
- Total width 1200 mm
- Total height 1300 mm



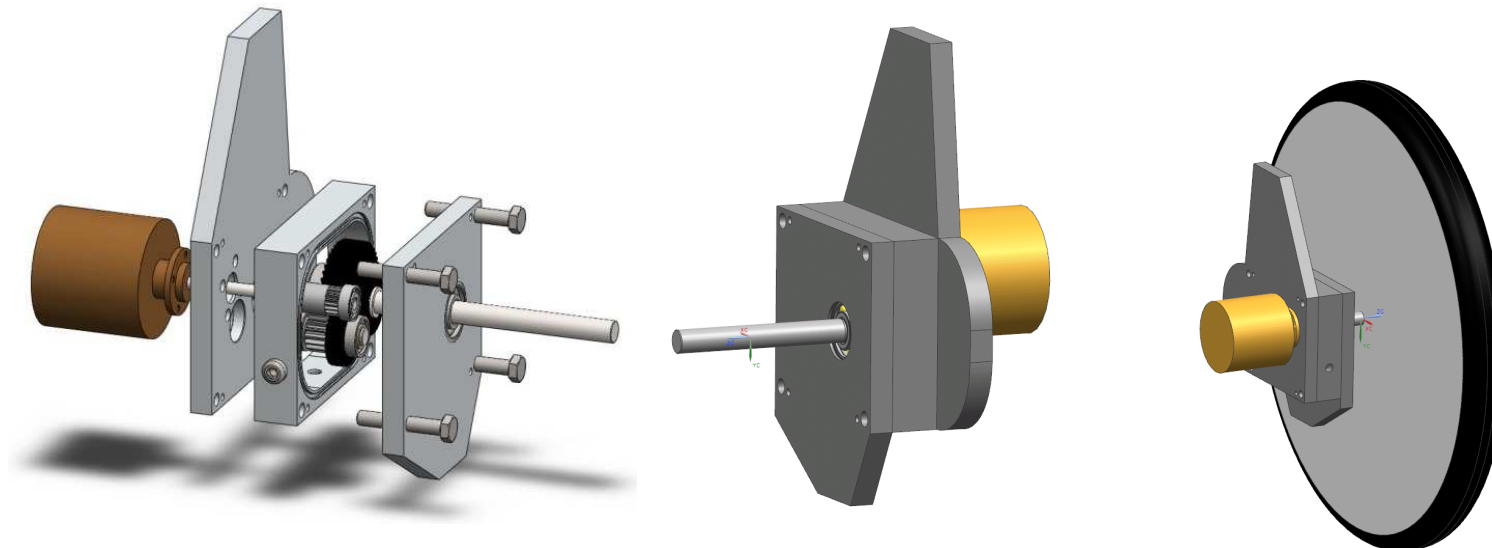
Chassis

- Aluminum 6060 T6 ($\sigma_{MAX.} = 35,55 \text{ N/mm}^2$)
- Total weight: 10 kg
- Finite elements analysis using NX Nastran



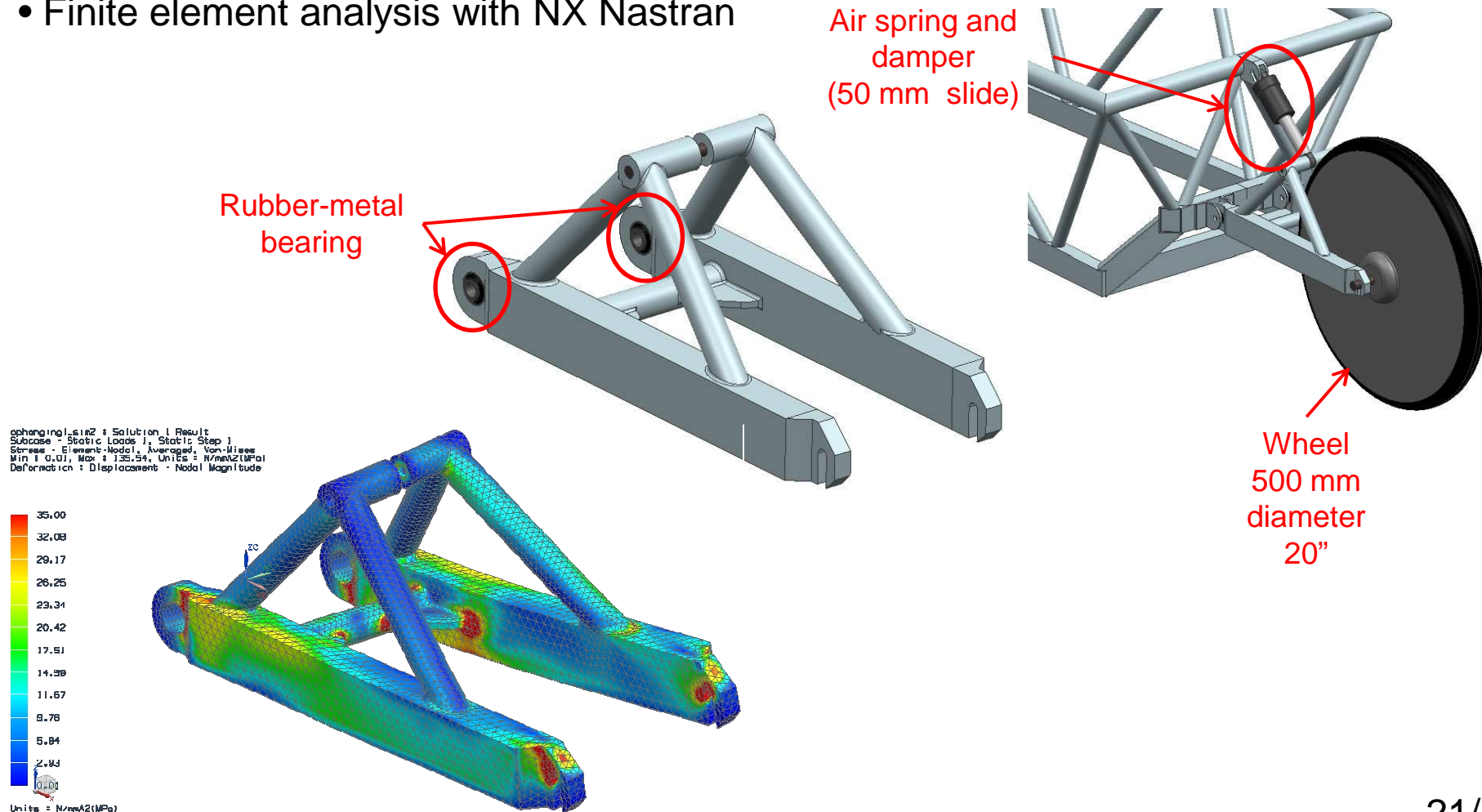
Reduction gear

- Drive and swivel shaft
- Motor:
 - Outer rotor permanent magnet synchronous
 - Brushless DC
- Two stage gear, later single stage
- Total weight (including motor): actual: 5,9 kg
but still can be made lighter



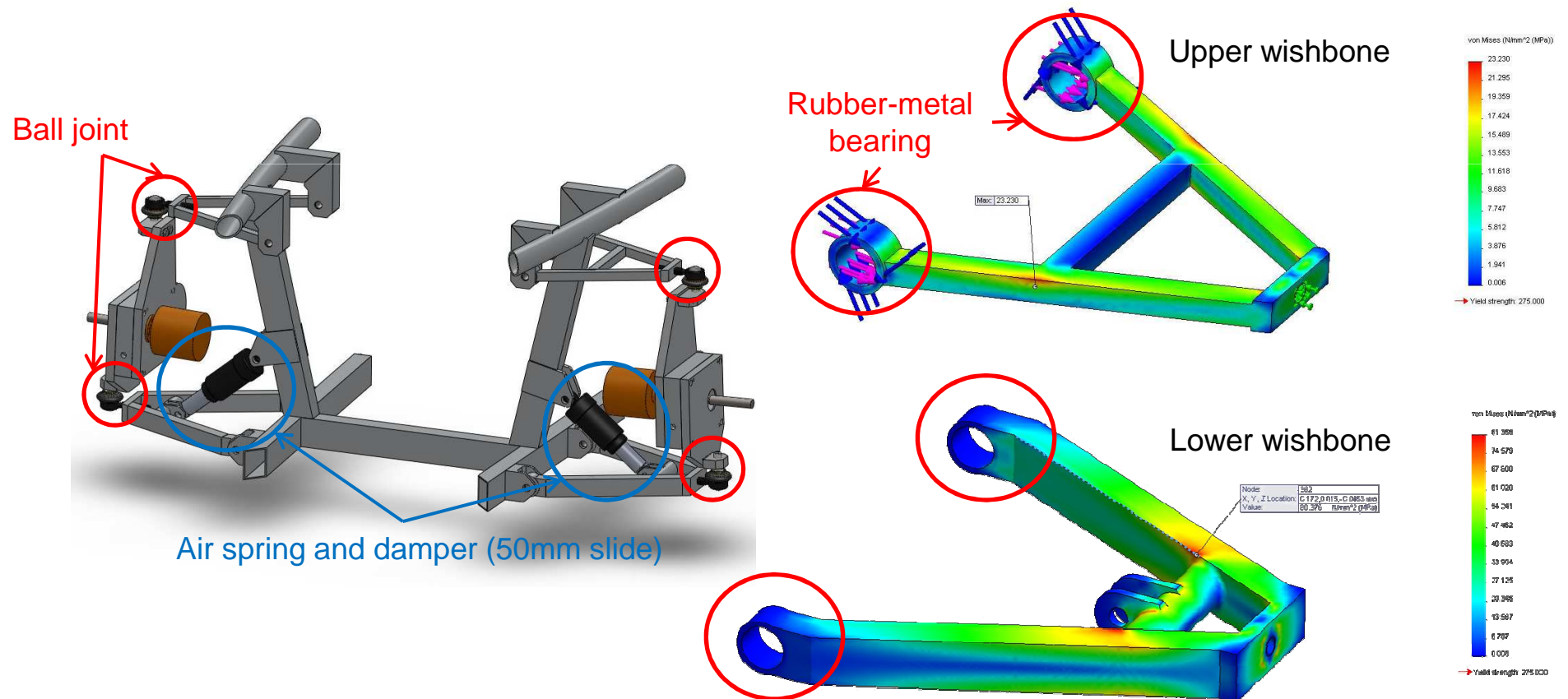
Rear suspension

- Aluminium 6060 T6 ($\sigma_{MAX.} = 35,55 \text{ N/mm}^2$)
- Total weight: 1,7 kg
- Finite element analysis with NX Nastran



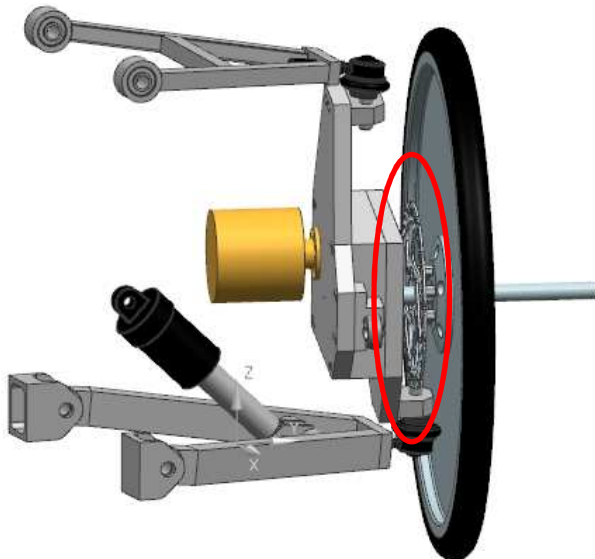
Front suspension

- Aluminum 6060 T6 ($\sigma_{MAX.} = 35,55 \text{ N/mm}^2$)
- Total weight: 2,5 kg
- Finite element analysis using Solidworks

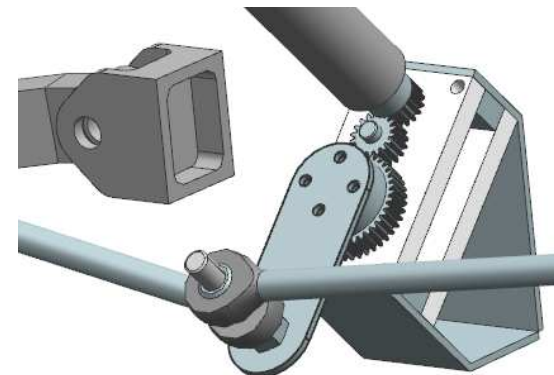
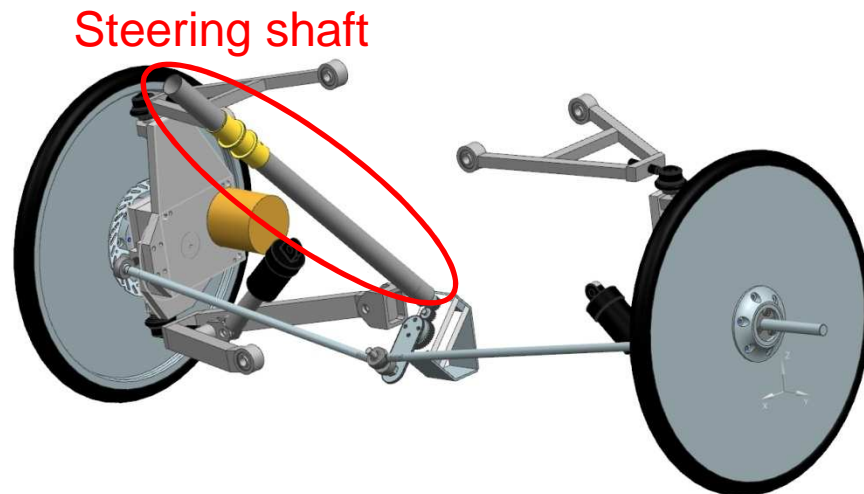
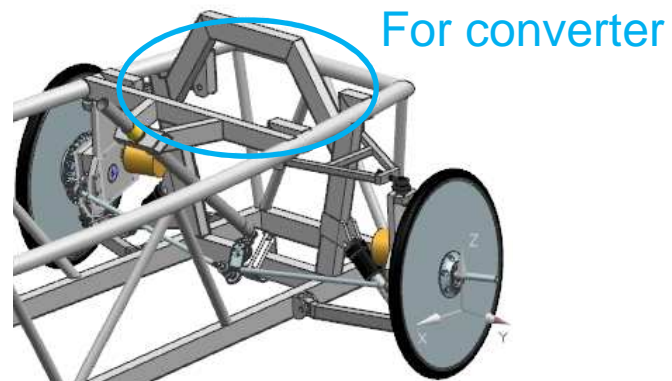


Brakes

- Electric by handle on the steering bar
 - Contactless gas and brake
- Mechanic by hydraulic brake (brake disc and claw)
 - Rear wheel
 - Each front wheel



Steering system



Batteries

+ battery management system

Batteries

- 2 battery packs of 48V (20Ah) in series

Cycle analyst

- Vehicle speed
- Odometer
- Electric information about the battery



Cycle
analyst

Battery

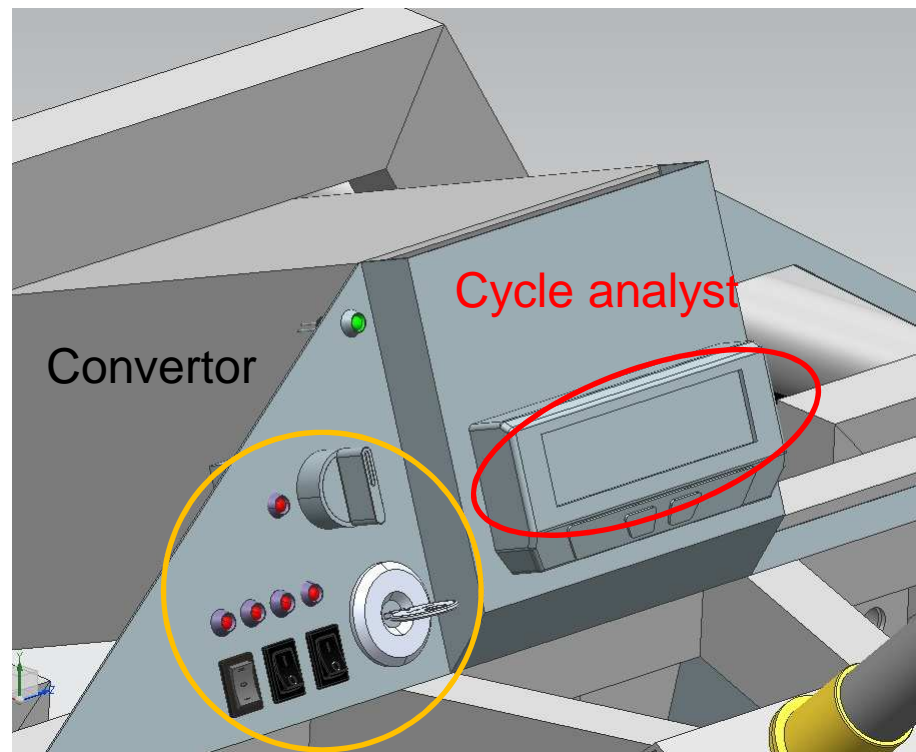


Battery charger



Dashboard

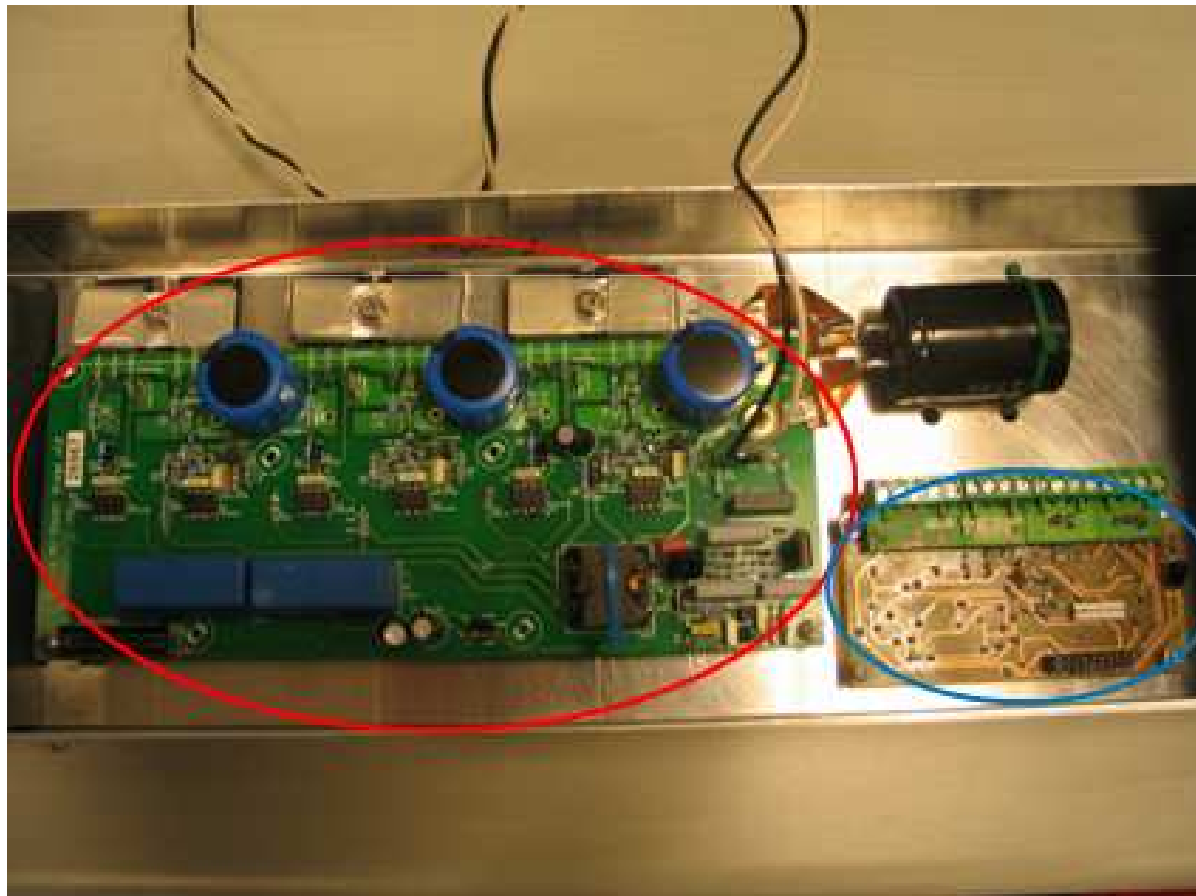
Is under construction



Indications and switches

Converter

Power stage



Control print

Converter

Power print

- Three phase converter
 - Torque control
 - Quadrant selection

Mosfet

Gate-driver

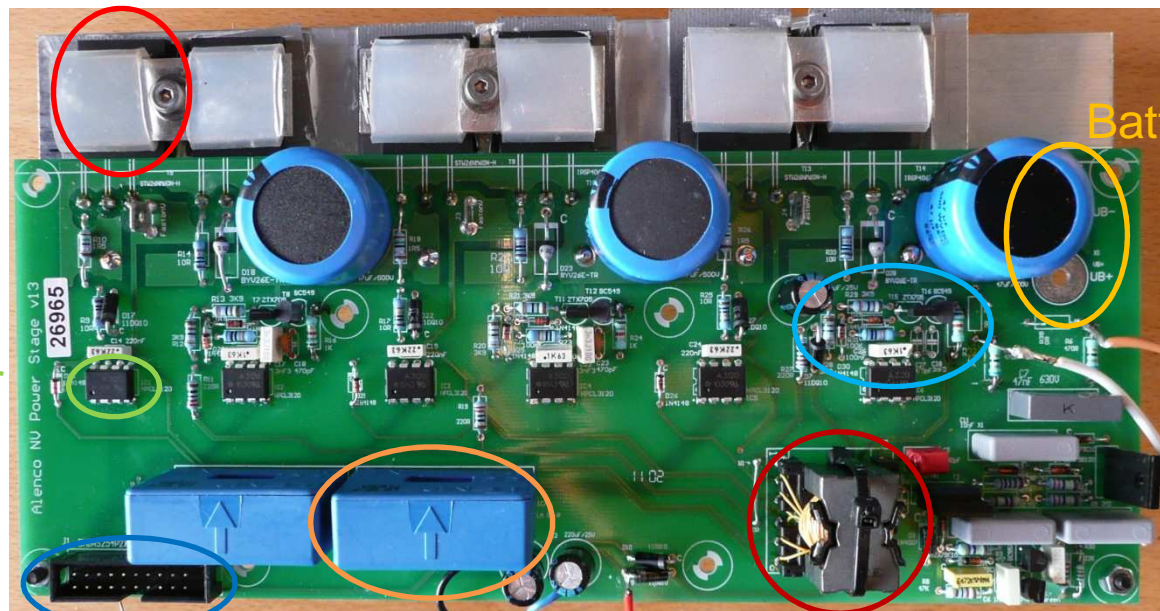
Battery input

Desaturation
protection

Control board
connection

LEM module

Internal supply



Converter

Control PCB

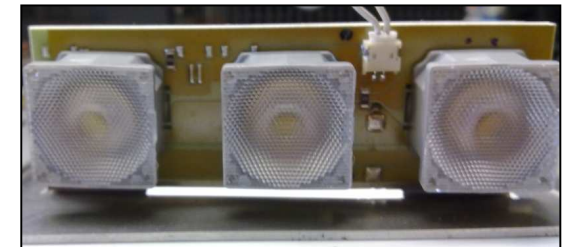
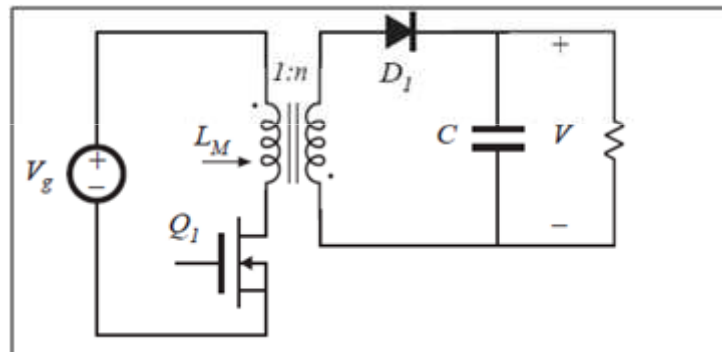
- Analog signals (brake- and gas handle)
 - Drive
 - Brake
- Digital signals
 - Torque direction (forward – reverse)
 - Enable (turn on- and off the BLDC)
 - Hall sensors for the position
 - Temperature protection for electronics
 - Temperature protection for motor



Motor and gear

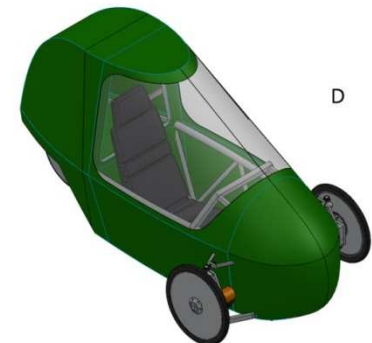
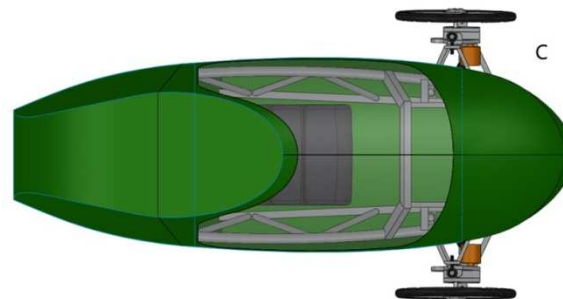
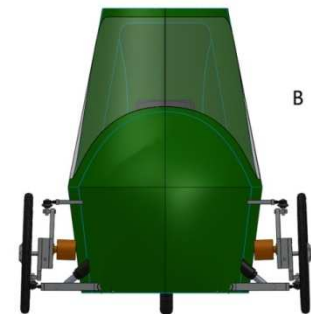
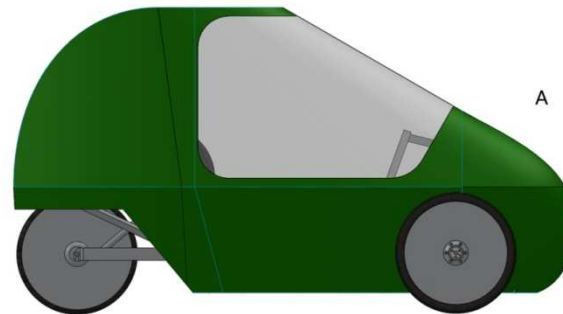
Lighting

- Flyback converter
 - Convert battery voltage(DC) to current for LEDs
 - High efficiency
- LED lighting
- 12V supply for control



Body shell

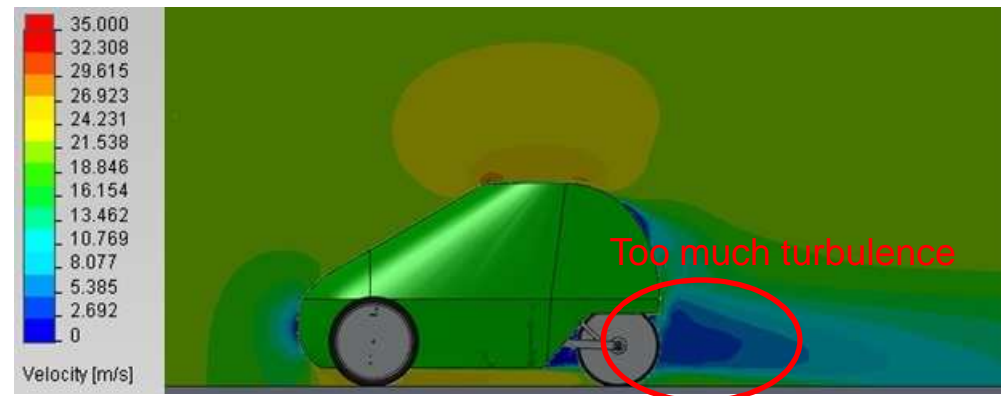
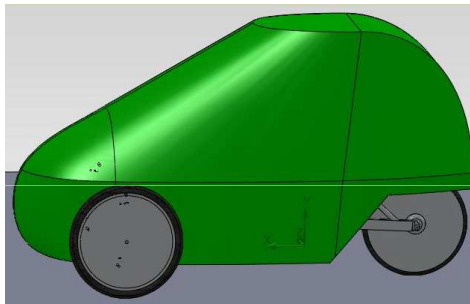
- Body panels
 - Bended plates (avoiding expensive molds)
- Lightweight
 - Insulating shell
- Safety
 - Cage for driver
- Aerodynamics
- Canopy (get in- and out)
- Tax plate support
- Luggage space



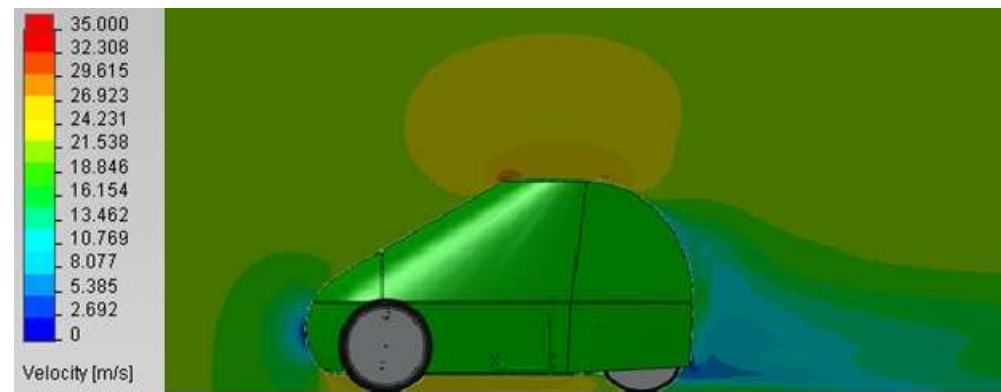
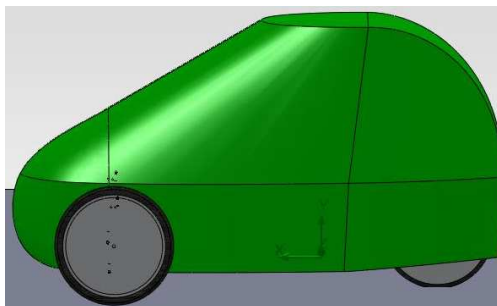
Aerodynamics

Influence of rear wheel cover

Model 1 body (Cd 0,32)

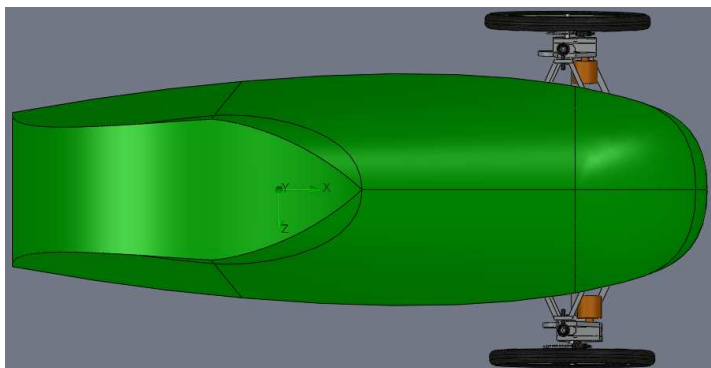
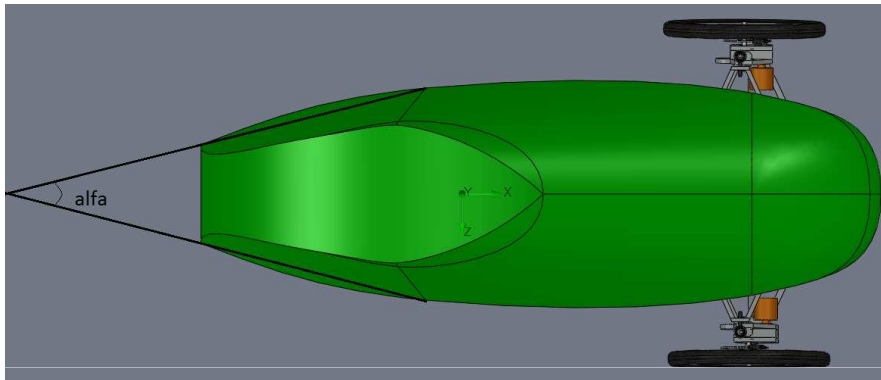


Model 2 body (Cd 0,28)

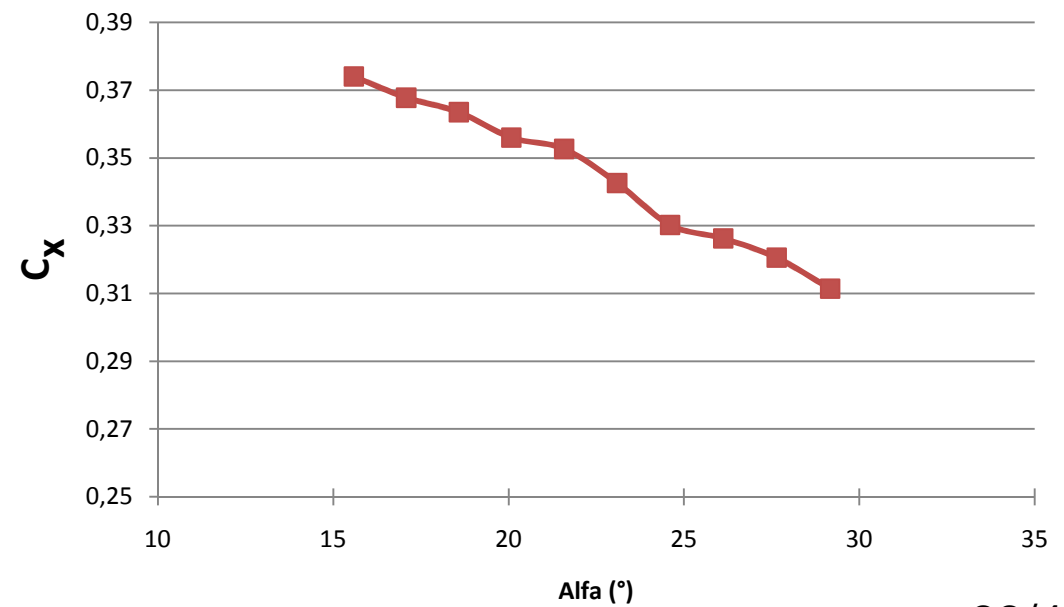


Aerodynamics

Influence of rear shape

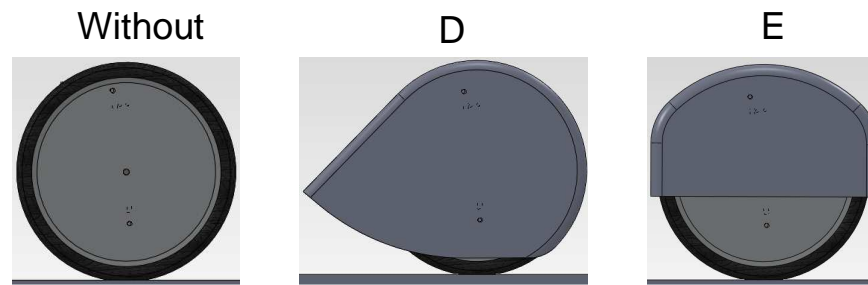
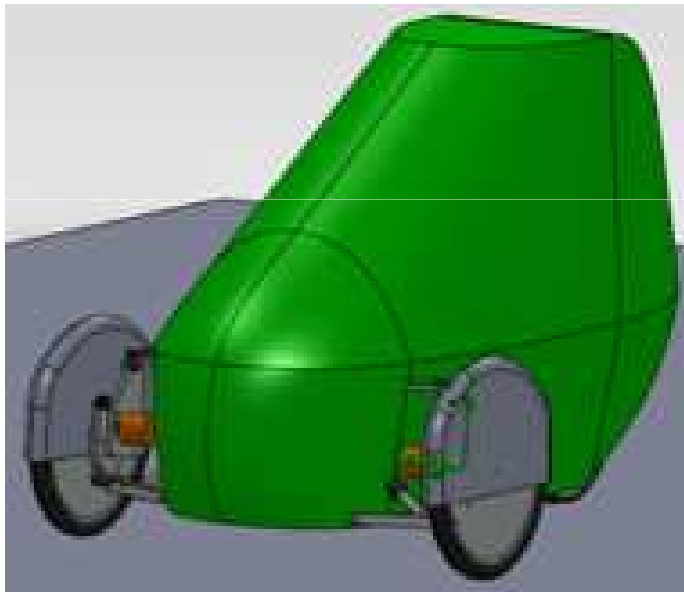


Influence of angle alfa on the C_x value

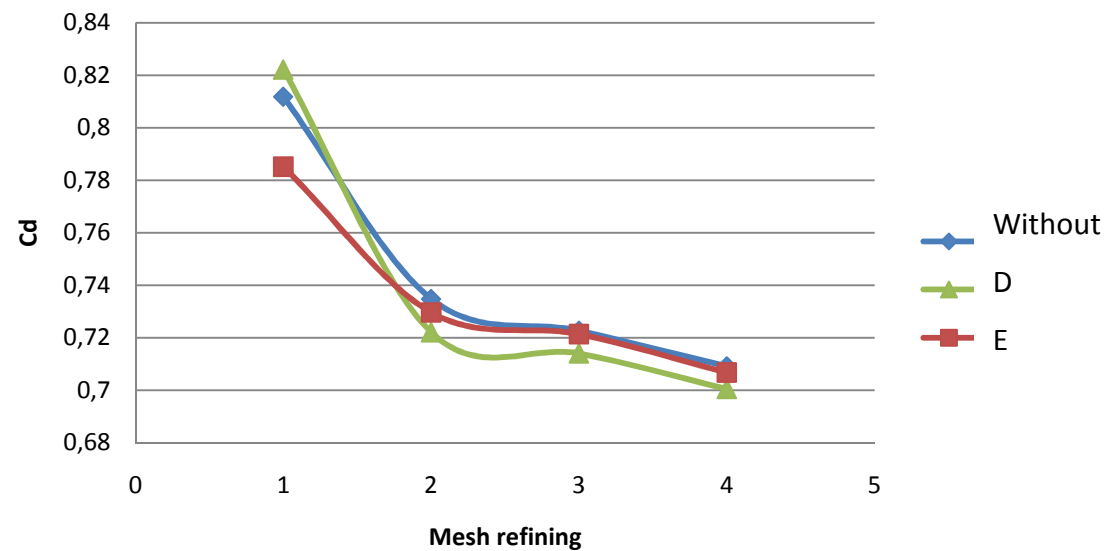


Aerodynamics

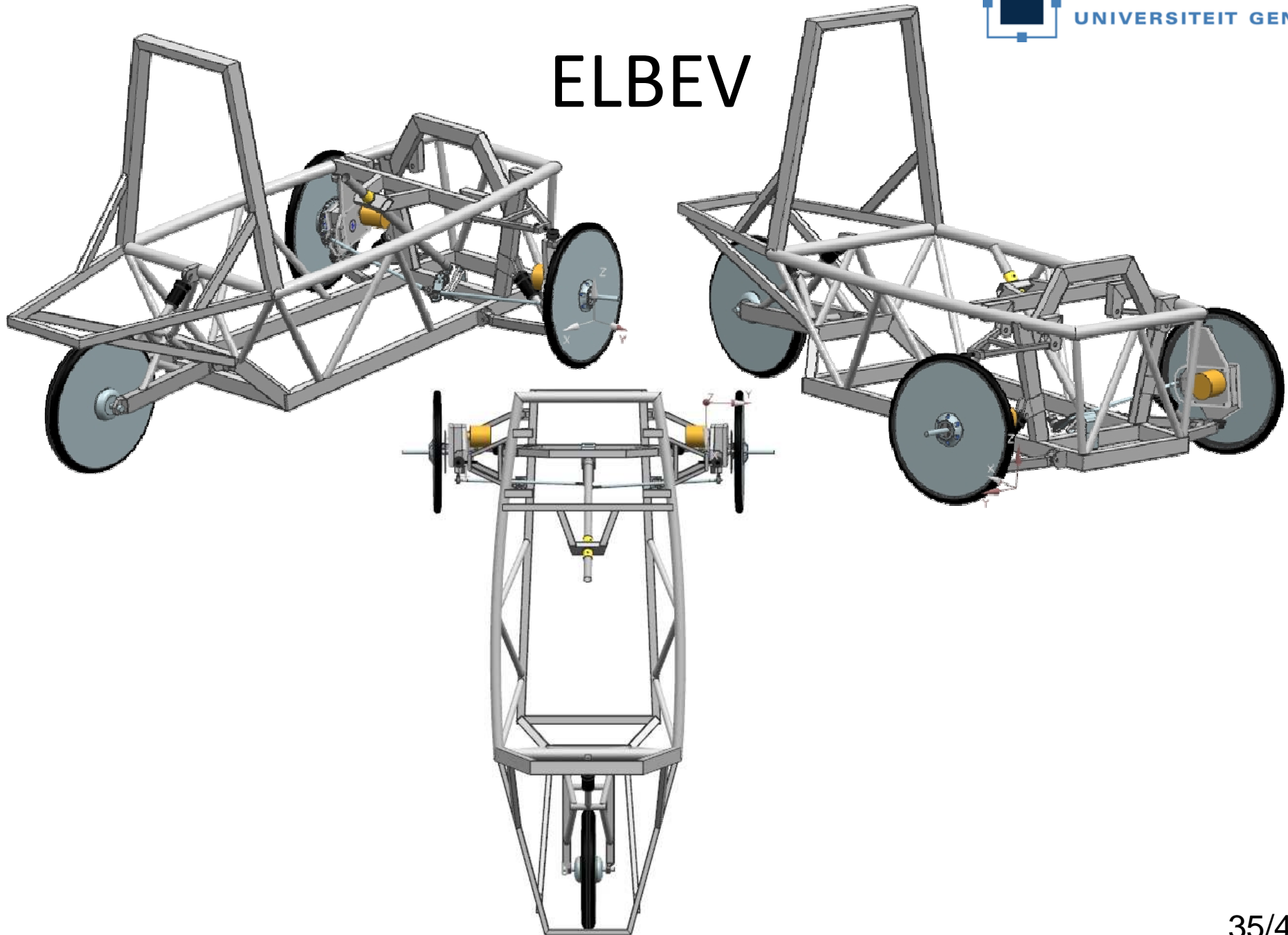
Fender optimisation of front wheels



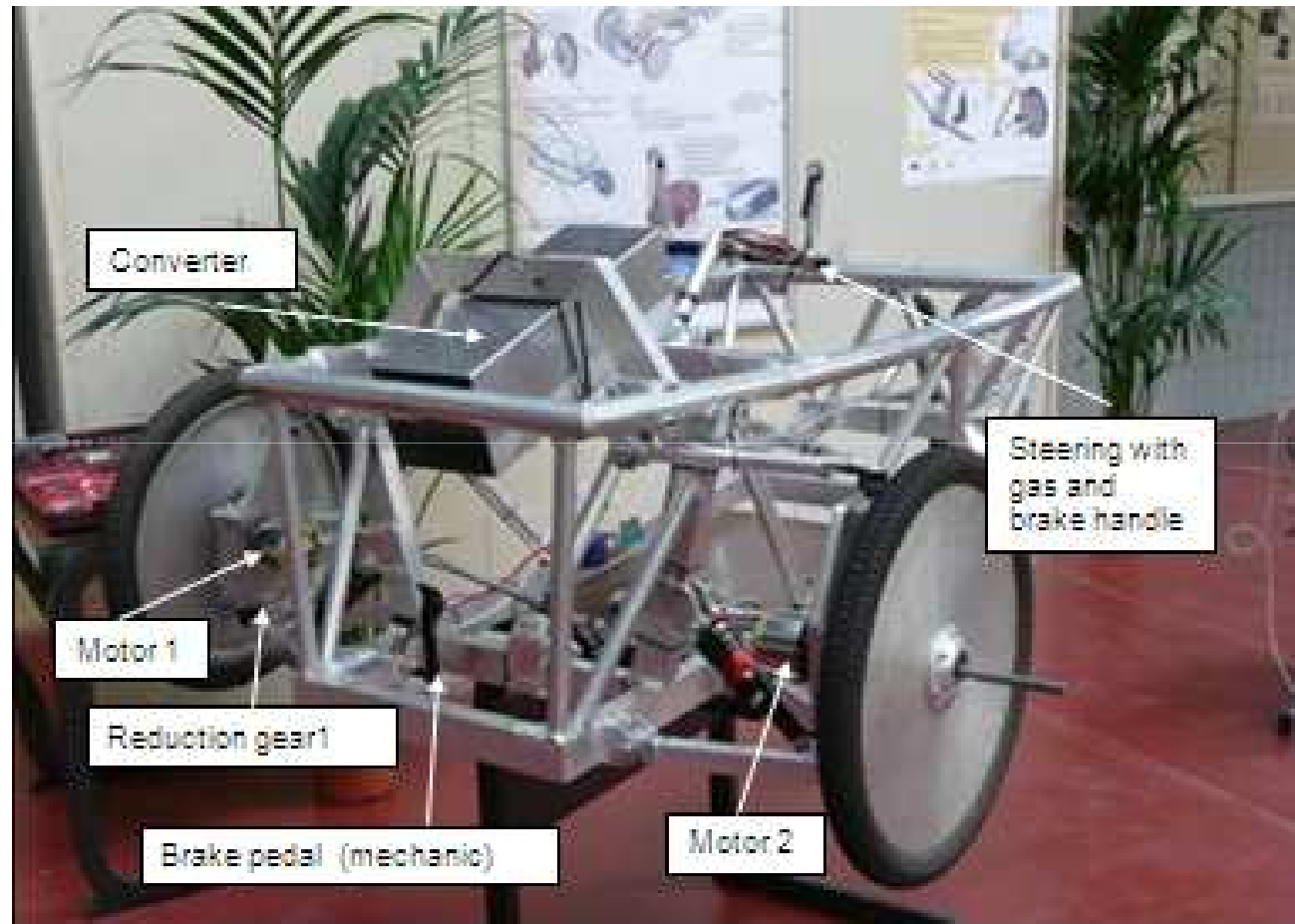
Fender simulations



ELBEV



ELBEV



First prototype of “elbev”

ELBEV

Addendum:

Predicted performance (with results of a model in mathcad):

4000W	peak power/motor, close to max. speed.
2000W	maximal continuous power close to maximum speed.
1500W	reference power/motor where the maximum efficiency is reached, at full speed.
90%	maximal efficiency point of drive, about: 95% electric 97% converter, 98% max mechanic
90%	battery efficiency at low current, but also an additional 0.1 ohm battery resistance is taken in account
10s	time to reach 50km/h
200kg	vehicle+driver mass
20Ah, 96V battery (=1.92kWh),	larger batteries result in a longer range, but higher price.
3W	auxiliary equipment (no light)

So, Losses include: Iron loss, Copper loss, conductors, wiring losses, equipment loss (no heating)

"Flat"	$C_{roll} = 0.01$, $C_x = 0.3$, $A = 0.9m^2$
"Mountain"	+ also 25% time 6% climb, 25% time 6% down, 50% flat.
"City"	Accelerate to listed speed each 1000m

With 2kWh/100km and a charger efficiency and of 90% 10000km/year one needs 2m² solar panel to compensate

ELBEV

Addendum: Predicted performance:

“Flat” $C_{roll} = 0.01$, $C_x = 0.3$, $A = 0.9m^2$
“Mountain” + also 25% time 6% climb, 25% time 6% down, 50% flat.
“City” Accelerate to listed speed each 1000m

Ecologic footprint? With

- 3kWh/100km
- a charger efficiency and of 90%
- 10000km/year

one needs 3m² solar panel to compensate: can it be more renewable?

Problem: regulations stop the development?

- Homologation
- EMC
- Crash tests (NCAP) not yet active for motorbikes
- Testing?

ELBEV

Addendum: Predicted performance

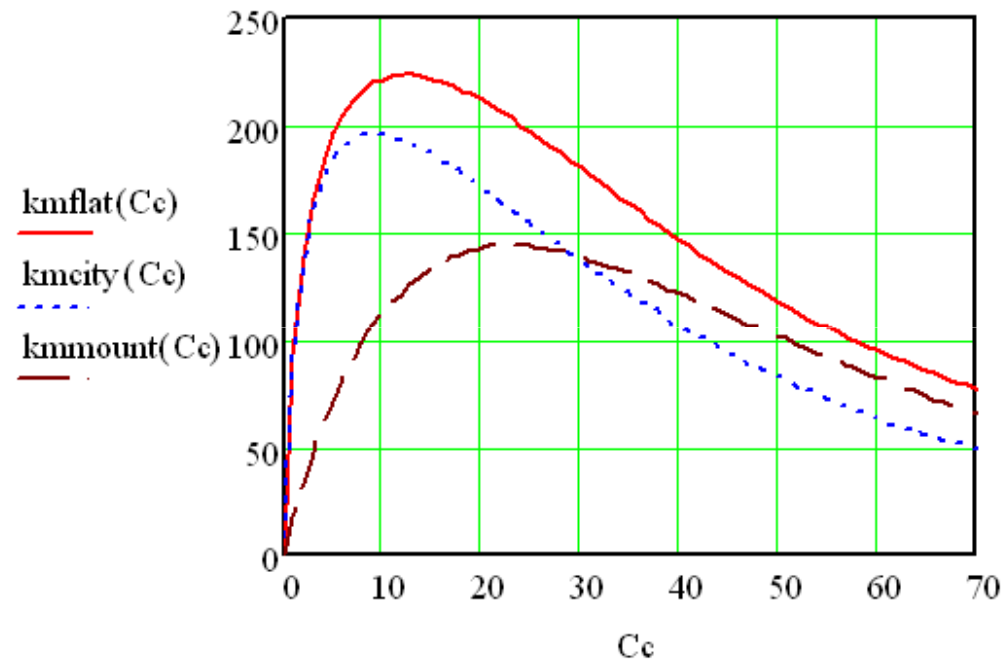


Fig. Predicted range as function of speed (in **km/h**) for different use, **3W** auxiliary

Note that:

- very low speeds are penalized by the auxiliary consumption
- very low speeds are not optimal at hill climbing.

ELBEV

Addendum: Predicted performance

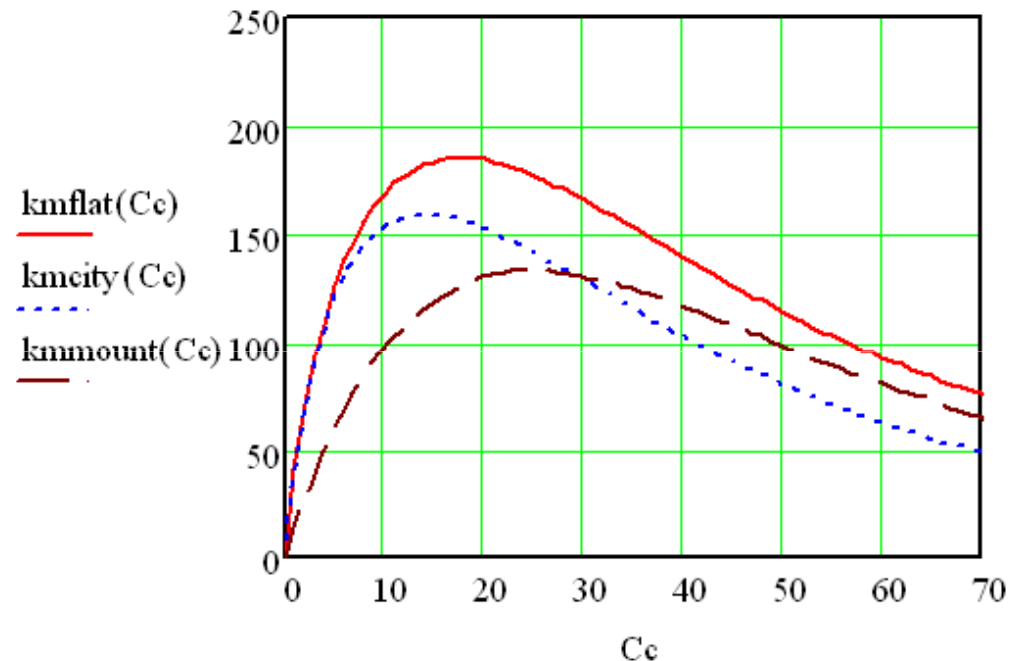


Fig. Predicted range as function of speed (in km/h) for different use, **30W** auxiliary

This means a heavy auxiliary consumption like wiper and light.
It reduces the range mainly below 30km/h.

This is the reason to use led lights and no separate 12V battery.

ELBEV

Conclusion:

- Ultralight electric vehicles are possible.
 - They need a very low energy
 - They still need investment and development
 - They can help us to reach European 2020 and 2050 energy goals
- What about the world need?
- What are the limiting factors in society?

